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# WAVELETS AND SELF-SIMILARITY: THEORY AND APPLICATIONS Lecture 4: Theory



# $\mathbf{P} \mathbf{L} \mathbf{A} \mathbf{N}$

1. SS + SSSI

- 2. STATIONARITY + LRD
- 3. SS + SSSI + Gaussian

4. ARFIMA

# **General Results**

• We assume that all random processes discussed are real valued and defined on the same parameter space.

Two processes X(t) and Y(t), equal in all finite dimensional distributions, will be denoted as  $X(t) \stackrel{d}{=} Y(t)$ . This means that for any selection of "times"  $0 \le t_1 < t_2 < \ldots t_k < \infty$  random vectors  $(X(\omega, t_1), \ldots, X(\omega, t_k))$ and  $(Y(\omega, t_1), \ldots, Y(\omega, t_k))$  have the same distribution. Informally, processes equal-in-distribution are statistically indistinguishable.

Random process X(t) is called stochastically continuous at  $t_0$  if  $\lim_{h\to 0} P(|X(t_0+h) - X(t_0)| > \epsilon) = 0$ , for any fixed  $\epsilon > 0$ .

Also, we consider processes not to be trivial. Process X(t) is trivial if the distribution of random variable  $X(\omega, t)$ , t fixed is a point mass measure.

A random process X(t), t > 0 is called *self-similar* if for any a > 0, there exists b > 0 such that

$$X(at) \stackrel{d}{=} bX(t).$$

■ (Lamperti, 1962) If random process  $X(t), t \ge 0$  is nontrivial, stochastically continuous at 0, and self-similar, then there exists unique  $H \ge 0$ such that  $b = a^H$ . If X(0) = 0, a.s. then H > 0.

Standard definition of self-similar processes is as follows: Process  $X(t), t \ge 0$  is self-similar, with self-similarity index H (*H*-ss) if and only if there exists H > 0 such that for any  $a > 0, X(at) \stackrel{d}{=} a^H X(t)$ .

Uniqueness of H is not obvious from this definition, although, H is unique by the Lamperti's theorem. Also, from Definition it follows X(0) = 0.

Example: Standard Brownian Motion B(t) is 1/2-ss. Indeed, the process  $W(t) = 1/\sqrt{a}B(at)$  is standard Brownian motion, as well.

# Stationarity and LRD

Let  $\{X(t), t \in \mathbb{R}\}$  be a random process such that the autocovariance function

$$\gamma_X(r,s) = \mathcal{COV}(X(r), X(s)) = E(X(r) - EX(r))(X(s) - EX(s))$$

is finite for any pair  $r, s \in \mathbb{R}$  The random process (time series)  $\{X(t), t \in \mathbb{R}\}$  is said to be (weakly, second-order, or wide-sense) stationary if

(i) 
$$E|X(t)|^2 < \infty$$
,  
(ii)  $EX(t) = m$ , for all  $t \in \mathbb{R}$ , and  
(iii)  $\gamma_X(r,s) = \gamma_X(r+t,s+t)$  for all  $r,s$ , and  $t \in \mathbb{R}$ .  
or

(iii)' 
$$\mathcal{COV}(X_{t+h}, X_t) = \gamma_X(h).$$

If the index space for parameter t is not  $\mathbb{R}$  but the set of integers,  $\mathbb{Z}$  random process X(t) is called random sequence or time series and often indexed as  $X_t, t \in \mathbb{Z}$ .

### Examples:

(i) White noise is a stationary sequence  $Z_t$  such that  $EZ_t = 0$  and  $\gamma(h) = \sigma^2 \cdot \delta_h$ ; in notation,  $Z_t \sim \mathcal{WN}(0, \sigma^2)$ .

(ii) The moving average MA(q) process, defined as

$$X_t = Z_t + \theta_1 Z_{t-1} + \theta_2 Z_{t-2} + \dots + \theta_q Z_{t-q}, \ Z_t \sim \mathcal{WN}(0, \sigma^2),$$

has autocovariance function

$$\gamma(h) = \begin{cases} \sigma^2 \sum_{j=0}^{q-|h|} \theta_j \theta_{j+|h|}, & |h| \le q \\ 0 & |h| > q. \end{cases}$$

(iii) The autoregressive AR(1) process,  $X_t - \phi X_{t-1} = Z_t$ ,  $Z_t \sim \mathcal{WN}(0, \sigma^2)$ , has autocovariance function

$$\gamma(h) = \sigma^2 \frac{\phi^{|h|}}{1 - \phi^2}.$$

Fourier transformation of autocorrelation (or autocovariance) function leads to spectral density  $f(\omega)$ 

$$f(\omega) = \int_{R} \gamma(h) e^{-ih\omega} dh,$$

which is non-negative by Wiener-Khinchine theorem. Properly normalized indeed represents a density in a probabilistic sense. Depending on the definition of Fourier transformation, in our case f should be divided by  $2\pi\gamma(0)$ .

The function  $f(\omega)$  is also called power-spectrum since  $E|X(t)|^2 = 1/(2\pi) \int_R f(\omega) d\omega$ , and  $E|X(t)|^2$  represents the "power" of zero-mean signal X(t).



■ It is possible define a counterpart of a spectral density of a nonstationary process (pseudo-spectrum) if linear filtering produces a stationary process. An example is spectrum for the fractional Brownian motion (later).

A stationary process Y(t) is called long-range dependent (LRD) process if its autocorrelation function or spectral density behave as

$$\gamma_Y(h) \sim C_\gamma |h|^{\alpha - 1}, \ h \to \infty, \alpha \in (0, 1),$$

or

$$f_Y(\omega) \sim C_f |\omega|^{-\alpha}, \ \omega \to 0, \alpha \in (0, 1),$$

where  $C_{\gamma}$  and  $C_f$  are two related constants. These two relations are equivalent subject to mild assumptions.



# SS + LRD

Let  $X(t), t \in R$  be H - ss process. If its increments are stationary, i.e., if the distribution of X(t+h) - X(t) is independent of t, it will be called H - sssi process.

The following theorem gives the form of autocorrelation function of any H - sssi process with finite second moment.

Let  $X(t), t \in \mathbb{R}$  be an H - sssi process for which  $E|X(1)|^2 < \infty$ . Then,

$$\gamma(t,s) = EX(t)X(s) = \frac{E|X(1)|^2}{2} \left[ |t|^{2H} + |s|^{2H} - |t-s|^{2H} \right].$$

**Proof:** From *H*-ss and stationarity of increments property,

$$EX(t)X(s) = \frac{1}{2} \left[ E(X(t)^2) + E(X(s)^2) - E[X(t) - X(s)]^2 \right]$$
  
$$= \frac{1}{2} \left[ t^{2H} E(X(1)^2) + s^{2H} E(X(1)^2) - E[X(|t-s|) - X(0)]^2 \right]$$
  
$$= \frac{E|X(1)|^2}{2} \left[ t^{2H} + s^{2H} - |t-s|^{2H} \right].$$

### Increments of SSSI processes

Let X(t) be an *H*-sssi process with 0 < H < 1 and  $E|X(1)|^2 < \infty$ . Define stationary sequence of random variables Y(n) as

$$Y(n) = X(n+1) - X(n).$$

If  $\gamma_Y(n)$  is the autocorrelation function for Y(n), i.e.,  $\gamma_Y(n) = EY(n)Y(0)$ , then if H = 1/2,  $\gamma_Y(n) = 0$ , for  $n \ge 1$  and if  $H \ne 1/2$ , it is possible to find an explicit expression for  $\gamma(n)$ . Using the fact that X(0) = 0 we find,

$$\gamma_Y(n) = EY(1)Y(n) = EX(1)(X(n+1) - X(n))$$
  
=  $E(X(1)X(n+1) - E(X(1)X(n)))$   
=  $\frac{E|X(1)|^2}{2} \left[ (n+1)^{2H} - n^{2H} + (n-1)^{2H} \right]$ 

If the expressions  $(n \pm 1)^{2H}$  are replaced by their polynomial expansions  $n^{2H} \pm 2Hn^{2H-1} + H(2H-1)n^{2H-2} + \dots$ , the following asymptotic result holds

$$\lim_{n \to \infty} \frac{\gamma_Y(n)}{H(2H-1)E|X(1)|^2 \ n^{2H-2}} = 1.$$
 (1)

In other words,  $\gamma_Y(n) = O(n^{2H-2})$ .

Note that series  $\sum_{n} |\gamma_{Y}(n)|$  converges if 2 - 2H > 1 or, equivalently, if 0 < H < 1/2. For such H, expression 2H - 1 in (1) is negative, and correlations  $\gamma_{Y}(n)$  are negative. If 1/2 < H < 1 correlations  $\gamma(n)$  are positive, but  $\sum_{n} |\gamma_{Y}(n)| = \infty$ , since 2 - 2H < 1.

# Aggregation

Long range dependent process Y(n) is asymptotically second-order self-similar, i.e., the second order moments of Y and aggregated time series  $Y^{(m)}$  coincide.

The aggregate series  $Y^{(m)}(k)$  is defined as series of averages of non-overlapping blocks of size m from the sequence Y(n),

$$Y^{(m)}(k) = \frac{Y(km - m + 1) + \dots + Y(km)}{m}$$

$$VarY^{(m)} \sim 1/m \ \gamma_Y(0) + \sum_{k=1}^{m-1} k^{2H-2}(m-k) \sim m^{2H-2}$$

Informally,  $Y^{(m)}(k)$  and Y(n) look similar at all scales. This asymptotic behavior of the variance of aggregated process,  $VarY^{(m)} \sim m^{2H-2}$ , can be used for inference about H.

# Self-Similar Processes as Fixed Points of Renormalization Groups

For a sequence of random variables  $Y_0, Y_1, \ldots, Y_n, \ldots, H > 0$ , and  $N \ge 1$  define the transformation

$$T_{N,H}: Y \longmapsto T_{N,H}Y = \{ (T_{N,H}Y)_j, \ j = 0, 1, 2, \dots \},\$$

where

$$(T_{N,H}Y)_j = \frac{1}{N} \sum_{k=jN}^{(j+1)N-1} Y_k, \ j = 0, 1, 2, \dots$$

■ It is easy to verify that

$$T_{M,H} \circ T_{N,H} = T_{MN,H},$$

and the sequence of transformations  $\{T_{N,H}, N = 1, 2, ...\}$  forms a multiplicative semigroup, called *renormalization group of index H*.

A stationary sequence  $Y = \{Y_0, Y_1, Y_2, ...\}$  is *H*-ss, if *Y* is a fixed point of a renormalization group  $\{T_{N,H}, N = 1, 2, ...\}$ , i.e., for any  $N \ge 1$  and any finite set of indices *J*,

$$\{(T_{N,H}Y)_j, j \in J\} \stackrel{d}{=} \{Y_j, j \in J\}.$$

Theorem: Let  $\{X(t), t \ge 0\}$  be *H*-sssi process with H > 0. Then the increment process  $Y_j = X(j+1) - X(j), \ j = 0, 1, 2, ...$  is a fixed point of the renormalization group  $\{T_{N,H}, N = 1, 2, ...\}$ .



**Proof.** Since  $\{X(t), t \ge 0\}$  is *H*-ss for H > 0, by Lamperti's Theorem, X(0) = 0. Fix any k > 0, and real numbers  $a_1, \ldots, a_k$ . Fix  $N \ge 1$ . Then,

$$\sum_{i=0}^{k} a_{i}(T_{N,H}Y)_{i} = \sum_{i=0}^{k} a_{i} \frac{1}{N^{H}} \sum_{j=iN}^{(i+1)N-1} Y_{j}$$
$$= \sum_{i=0}^{k} a_{i} \frac{1}{N^{H}} (X((i+1)N) - X(iN))$$
$$\stackrel{d}{=} \sum_{i=0}^{k} a_{i} (X(i+1) - X(i))$$
$$= \sum_{i=0}^{k} a_{i} Y_{i}.$$

Time domain exponent  $n^{2H-2}$  corresponds to frequency domain exponent  $\omega^{1-2H}$ . Thus frequency scaling is,

i=0

$$\alpha = 2H - 1,$$

# Fractional Brownian Motion (fBm) and Fractional Gaussian Noise (fGn)

Fractional Brownian motion (fBm) is a generalization of standard Brownian motion (Wienner Process). The Brownian motion B(t) is standardly defined as a random process satisfying the following four requirements:

(i) B(0) = 0,

- (ii) For any choice n and  $0 \le t_1 < t_2 < \cdots < t_n$ , the increments  $B(t_2) B(t_1), \ldots, B(t_n) B(t_{n-1})$  are independent and stationary;
- (iii) For fixed t, B(t) is the Gaussian random variable with zero mean and variance t, and
- (iv) B(t) is a continuous function of t, a.s.

It is straightforward to check that the Brownian motion is an 1/2-sssi process, for  $W(t) = a^{-1/2}B(at)$  conforms to properties (i)-(iv).

The Brownian motion is a Gaussian process and Gaussian processes are fully determined by their second order properties. Thus, the Brownian motion is *unique* Gaussian process having covariance function  $\gamma(t,s) = EB(t)B(s) = 1/2(t+s-|t-s|) = \min\{t,s\}.$ 

■ If H-sssi process is Gaussian, it is unique and it is called **fractional** Brownian motion.

**Def.** A zero mean Gaussian process  $B_H(t)$  is called fractional Brownian motion with Hurst exponent H, if

$$EX(t)X(s) = \frac{E|X(1)|^2}{2} \left[ |t|^{2H} + |s|^{2H} - |t-s|^{2H} \right],$$

where  $E|X(1)|^2 = \frac{\Gamma(2-2H)\cos(\pi H)}{\pi H(1-2H)}$ .

The process  $B_H(t)$  is unique, in the sense that class of all fractional Brownian motions with exponent H coincides with the class of all Gaussian H - ss processes. However, a Gaussian process is H - ss with independent increments, if and only if it H = 1/2, i.e., if it is a Brownian motion.

### $\blacksquare Alternative Definition (1)$

- (i)  $B_H(t)$  has stationary increments,
- (ii)  $B_H(0) = 0$  and  $\mathbb{E}B_H(t) = 0 \forall t$
- (iii)  $\mathbb{E}B_H(t)^2 = |t|^{2H}, \forall t$
- (iv)  $B_H(t)$  is a Gaussian process
- (v)  $B_H(t)$  has continuous paths.

■ The difference process,  $Y_n = B_H(n+1) - B_H(n)$  is called fractional Gaussian noise (fGn). The covariance function of fGn is

$$\gamma(h) = \frac{E|X(1)|^2}{2} \left[ (h+1)^{2H} - 2h^{2H} + (h-1)^{2H} \right],$$

which is, as we discussed, in agreement with general H-sssi processes.

Since  $B_H(t)$  is the unique Gaussian *H*-sssi process, it follows from Renormalization Theorem that in the class of Gaussian stationary sequences, the fractional Gaussian noise is *unique* fixed point of the renormalization group  $\{T_{N,H}, N = 1, 2, ...\}$ .

■ Alternative Definition (2): Mandelbrot and Van Ness (1968)

$$B_{H}(0) = 0, \text{ and}$$

$$B_{H}(t) = C \cdot \left[ \int_{-\infty}^{t} (t-s)^{H-1/2} B(ds) - \int_{0}^{t} (-s)^{H-1/2} B(ds) \right]$$

$$= \int K(t,s) \ B(ds), \text{ where } C = \Gamma(H+1/2) / (\Gamma(2H+1)\sin(\pi H))^{1/2}.$$

 $\blacksquare$   $B_H(t)$  is selfsimilar with self-similarity index H

$$B_H(ct) = \int K(ct,s) \ B(ds) = c^{H-1/2} \int K(t,s/c) \ B(ds)$$
  
=  $c^{H-1/2} \int K(t,v) \ B(dv) = c^{H-1/2} c^{1/2} \int K(t,v) \ B(dv) = c^H B_H(t).$ 

■ Similarly to integral representation of Mandelbrot and Van Ness, fBm allows the so called harmonizable representation,

$$B_H(t) = \int_{\mathbb{R}} \frac{e^{it\omega} - 1}{|\omega|^{H+1/2}} B(d\omega),$$

where  $B(d\omega)$  is the Wiener measure.

Sample paths of fractional Brownian motion are behaving similarly to those of standard Brownian motion. They are continuous almost surely for all  $H \in (0, 1)$  and nowhere differentiable. The fractal (Hausdorff) dimension of sample paths is D = 2 - H. That means that for small H (say, H < 0.5) the sample paths are quite irregular and *space-filling*.



Simulated paths of fractional Brownian motion, (a) H = 1/4, (b) H = 1/2, and (c) H = 3/4.

It is interesting that sample paths of fractional Brownian motions are continuous in H, a result of Peltier and Lévy-Véhel (2000).

# **Convex Rearrangements of Davidov**

• Let  $\Delta(i) = B_H(\frac{i+1}{n}) - B_H(\frac{i}{n})$ , for  $i = 1, \ldots, n-1$ . Let  $\Delta_{1:n} \leq \ldots \Delta_{n:n}$  be the corresponding order statistics. Define the polynomial  $VB_{H,n}(t) = \sum_{i=0}^{[nt]-1} \Delta_{i:n} + (nt - [nt])\Delta_{[nt]:n}.$ 

**[Th]** Phillpe and Thilly (2000) showed that

$$\frac{VB_{H,n}(t)}{n^{1-H}\sqrt{C}} \to L(t),$$

where  $L(t) = -\frac{1}{\sqrt{2\pi}} \exp{-\frac{1}{2}\Phi^{-1}(t)}$ , and  $\Phi$  is the standard Gaussian cdf. This result can be utilized to estimate H.

# Autoregressive, Fractionally Integrated, Moving Average Processes (ARFIMA)

ARFIMA(p, d, q) introduced by Granger and Joyeux (1980) and Hosking (1981).

It can be used for statistical modeling of time series with long memory. ARMA models (when d = 0) or ARIMA (when d is a positive integer) are special cases.

In the terms of standard time back-lag operator B defined as  $B^k Y(n) = Y(n-k), \ k = 0, 1, \ldots$ , the ARFIMA(p, d, q) model can be represented as:

$$\Phi_p(B)(1-B)^d Y(n) = \Theta_q(B)\epsilon(n), \quad n = 1, 2, \dots$$

where  $\Phi_p(z) = 1 - \phi_1 z - \cdots - \phi_p z^p$  is the autoregressive polynomial and  $\Theta_q(z) = 1 + \theta_1 z + \cdots + \theta_q z^q$  is the moving average polynomial; p and q are integers, and d is a real number from (-1/2, 1/2). The innovations  $\epsilon(n)$  are assumed i.i.d. normal with zero mean and variance  $\sigma^2$ .

The ARFIMA(p, d, q) model can be interpreted as an ARMA(p, q) process

$$\Phi(B)Y(n) = \Theta(B)Z(n), n = 1, 2, \dots$$

where the noise process Z(n) is a fractionally differenced Gaussian noise,

$$(1-B)^d Z(n) = \epsilon(n), \ \epsilon(n) \sim N(0, \sigma^2).$$

We will focus on ARFIMA(0, d, 0) since, for example, ARFIMA(p, d, q) model can be generated by appropriate filtering of ARFIMA(0, d, 0). For example, in MATLAB, to obtain an ARFIMA(p, d, q) simulation from an ARFIMA(0, d, 0)run, one applies filter function,

arfimapdq = filter( b, a, arfima0d0 ), where a =  $\begin{bmatrix} 1 & -\phi_1 & -\phi_2 & \dots & -\phi_p \end{bmatrix}$  and b =  $\begin{bmatrix} 1 & \theta_1 & \theta_2 & \dots & \theta_q \end{bmatrix}$ .

The fractional difference operator can be expresses by the following binomial expansion:

$$(1-B)^{d} = \sum_{k=0}^{\infty} {\binom{d}{k}} (-B)^{k}$$
  
=  $1 - dB - \frac{1}{2}d(1-d)B^{2} - \frac{1}{6}d(1-d)(2-d)B^{3} - \dots + (-1)^{k} \frac{\Gamma(d+1)}{\Gamma(k+1)\Gamma(d-k+1)}B^{k} + \dots$ 

■ It holds  $(-1)^k \frac{\Gamma(d+1)}{\Gamma(k+1)\Gamma(d-k+1)} = \prod_{0 < j \le k} \frac{k-1-d}{k} = c_k$ , so ARFIMA(0, d, 0) is an AR(∞) process. In particular, ARFIMA(0, d, 0) is close to fractional Gaussian noise with parameter H = d + 1/2.

For d > 1/2 the ARFIMA process is not stationary, although it can be differenced to a stationary process. For -0.5 < d < 0 the process is called intermediate memory or *overdifferenced*, see Brockwell and Davis (1993). The ARFIMA model is stationary with long memory when when 0 < d < 1/2, which is the most interesting case.





The process Z(n) can also be represented as an moving average process of infinite order, since

$$Z(n) = (1 - B)^{-d} \epsilon(n), \ \epsilon(n) \sim \mathcal{N}(0, \sigma^2)$$
(2)

can be written as

$$Z(n) = \sum_{k=0}^{\infty} {\binom{d+k-1}{k}} \epsilon(n-k)$$
$$= \sum_{k=0}^{\infty} \frac{\Gamma(k+d)}{\Gamma(k+1)\Gamma(d)} \epsilon(n-k)$$

The covariance function of Z(t) is given as

$$\gamma_Z(h) = E(Z(n)Z(n+h)) =$$
  
=  $\gamma(0) \frac{\Gamma(1-d)\Gamma(h+d)}{\Gamma(d)\Gamma(h+1-d)}$  (3)

$$= \gamma(0) \prod_{0 < k \le h} \frac{k - 1 + d}{k - d}, \ h = 1, 2, \dots$$

where  $\gamma(0) = \sigma^2 \sum_{k=0}^{\infty} {\binom{d+k-1}{k}}^2 = \frac{\sigma^2}{\sqrt{\pi} \cdot 4^d} \frac{\Gamma(1/2-d)}{\Gamma(1-d)}.$ 

Autocorrelation function can be represented as

$$\rho(h) = \gamma(h) / \gamma(0) = \prod_{0 < k \le h} \frac{k - 1 + d}{k - d} = \frac{d(1 + d) \dots (h - 1 + d)}{(1 - d)(2 - d) \dots (h - d)}, \ h = 1, 2, \dots$$

Since  $\frac{\Gamma(h+a)}{\Gamma(h+b)} \sim h^{a-b}$ , when h is large,  $\rho(h) \sim \frac{\Gamma(1-d)}{\gamma(d)} h^{2d-1}$ . Obviously, when 0 < d < 0.5, the exponent -1 < 2d - 1 < 0 and the series  $\sum_{h} \rho(h)$  diverges ("long memory").

■ By filtering considerations, the spectral density of an ARFIMA(p, d, q) process is

$$f(\omega) = \frac{\sigma^2}{2\pi} |1 - e^{-i\omega}|^{-2d} \frac{|\Theta(e^{-i\omega})|^2}{|\Phi(e^{-i\omega})|^2}.$$

Since  $|1 - e^{-i\omega}|^2 = 4\sin^2(\omega/2) \sim 4(\frac{\omega}{2})^2$ , as  $\omega \to 0$ , the spectral density of ARFIMA(p, d, q) process behaves as

$$f(\omega) \sim \frac{\sigma^2}{2\pi} |\omega|^{-2d} \frac{|\Theta(1)|^2}{|\Phi(1)|^2},$$

when  $\omega$  is close to 0.

Expressions for autocovariance function for general ARFIMA(p, d, q) are complicated.